

SageMatrixFactorizationDemo260831

September 4, 2026

1 Matrix generators

```
[1]: def sgen(i,c,t):  
    """  
    returns the generator  $s_i(c)$   
    """  
    M=MatrixSpace(QQ,t,t)  
    I=identity_matrix(QQ, t)  
    E=M.basis()  
    return( I-E[i-1,i-1]-E[i,i]+E[i-1,i]+E[i,i-1]+c*E[i-1,i-1] )
```

```
[2]: def sinv(i,c,t):  
    """  
    returns  $s_i(c)^{-1}$   
    """  
    M=MatrixSpace(QQ,t,t)  
    E=M.basis()  
    I=identity_matrix(QQ, t)  
    return( I-E[i-1,i-1]-E[i,i]+E[i-1,i]+E[i,i-1]-c*E[i,i] )
```

```
[3]: def hgen(i,c,t):  
    """  
    returns the generator  $h_i(c)$   
    """  
    M=MatrixSpace(QQ,t,t)  
    E=M.basis()  
    I=identity_matrix(QQ, t)  
    return( I+(c-1)*E[i-1,i-1] )
```

```
[4]: def xgen(i,j,c,t):  
    """  
    returns the generator  $x_{ij}i(c)$   
    """  
    M=MatrixSpace(QQ,t,t)  
    E=M.basis()  
    I=identity_matrix(QQ, t)  
    if i < j:
```

```

    return( I + c*E[i-1,j-1] )
else:
    print("must have i not equal to j in x(i,j,c) so returning 1")
    return(I)

```

```
[5]: sgen(3,2,4)
```

```
[5]: [1 0 0 0]
      [0 1 0 0]
      [0 0 2 1]
      [0 0 1 0]
```

```
[6]: sinv(2,5,4)
```

```
[6]: [ 1  0  0  0]
      [ 0  0  1  0]
      [ 0  1 -5  0]
      [ 0  0  0  1]
```

```
[7]: hgen(2,5,4)
```

```
[7]: [1 0 0 0]
      [0 5 0 0]
      [0 0 1 0]
      [0 0 0 1]
```

```
[8]: xgen(2,3,7,4)
```

```
[8]: [1 0 0 0]
      [0 1 7 0]
      [0 0 1 0]
      [0 0 0 1]
```

2 Some matrices for examples

```
[9]: M46=MatrixSpace(QQ,4,6)
```

```
[10]: M55=MatrixSpace(QQ,5,5)
```

```
[11]: A=M46([-3,-36,-39,-42,-46,-84, -9,-108,-233/2,-114,-247/2,-167,
↪3,36,39,42,45,48, 0,0,1/4,6,25/4,13/2])
```

```
[12]: A
```

```
[12]: [ -3  -36  -39  -42  -46  -84]
      [ -9  -108 -233/2 -114 -247/2 -167]
      [  3   36   39   42   45   48]
```

[0 0 1/4 6 25/4 13/2]

[13]: $B0 = M46([3, 36, 39, 42, 45, 48, 0, 0, 1/4, 6, 25/4, 13/2, 0, 0, 0, 0, -1, -36, 0, 0, 0, 0, 0, 0])$

[14]: B0

[14]: $\begin{bmatrix} 3 & 36 & 39 & 42 & 45 & 48 \\ 0 & 0 & 1/4 & 6 & 25/4 & 13/2 \\ 0 & 0 & 0 & 0 & -1 & -36 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$

[15]: $C0 = M46([1, 12, 13, 14, 15, 16, 0, 0, 1, 24, 25, 26, 0, 0, 0, 0, 1, 36, 0, 0, 0, 0, 0, 0])$

[16]: C0

[16]: $\begin{bmatrix} 1 & 12 & 13 & 14 & 15 & 16 \\ 0 & 0 & 1 & 24 & 25 & 26 \\ 0 & 0 & 0 & 0 & 1 & 36 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$

[17]: $V = M55([4, 7, 9, 10, 1, 3, 6, 8, 1, 0, 2, 5, 1, 0, 0, 1, 1, 0, 0, 0, 1, 0, 0, 0, 0])$

[18]: V

[18]: $\begin{bmatrix} 4 & 7 & 9 & 10 & 1 \\ 3 & 6 & 8 & 1 & 0 \\ 2 & 5 & 1 & 0 & 0 \\ 1 & 1 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \end{bmatrix}$

[19]: $w0 = M55([0, 0, 0, 0, 1, 0, 0, 0, 1, 0, 0, 0, 1, 0, 0, 0, 1, 0, 0, 0, 0, 1, 0, 0, 0])$

[20]: w0

[20]: $\begin{bmatrix} 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \end{bmatrix}$

[21]: $U = M55([1, 10, 9, 7, 4, 0, 1, 8, 6, 3, 0, 0, 1, 5, 2, 0, 0, 0, 1, 1, 0, 0, 0, 0, 1])$

[22]: U

[22]: $\begin{bmatrix} 1 & 10 & 9 & 7 & 4 \\ 0 & 1 & 8 & 6 & 3 \\ 0 & 0 & 1 & 5 & 2 \\ 0 & 0 & 0 & 1 & 1 \end{bmatrix}$

```
[ 0  0  0  0  1]
```

3 First nonzero sequence, rank and status checks

```
[23]: def fnz(A):  
    r"""  
    Constructs the first non-zero sequence of A, i.e.  
    the sequence recording the position of the first nonzero  
    entry in each row of A  
    """  
    f = [-1]  
    t = A.nrows()  
    s = A.ncols()  
    for i in range(t):  
        nonzero_list = [j for j in range(s) if A[i,j] != 0]  
        if len([j for j in range(s) if A[i,j] != 0])>0:  
            fi = min([j for j in range(s) if A[i,j] != 0])  
        else:  
            fi = None  
        f.append(fi)  
    return(f)
```

```
[24]: def finccheck(f):  
    r"""  
    Checks if the sequence f is strictly increasing  
    """  
    for i in range(1,len(f)):  
        if f[i-1] == None and f[i] != None:  
            return(False)  
        if f[i-1] != None and f[i] != None and f[i] <= f[i-1]:  
            return(False)  
    else:  
        return(True)
```

```
[25]: def ifonecheck(A):  
    r"""  
    Checks that A is in echelon form and that the first nonzero entry in each  
    nonzero row is 1  
    """  
    f = fnz(A)  
    if finccheck(f) == True:  
        r = erank(A)  
        for i in range(1, r+1):  
            if A[i-1, f[i]] != 1:  
                return(False)  
        else:
```

```
return(True)
```

```
[26]: def xredcheck(A):  
    r"""  
    This checks that A is in echelon form and that the first nonzero entry in  
    ↪ each nonzero row is 1 and that the entries  
    above the first nonzero in each row are all 0  
    """  
    f = fnz(A)  
    if finccheck(f) == False:  
        print("the matrix is not in echelon form")  
        return(False)  
    elif ifonecheck(A) == False:  
        print("the matrix is in echelon form but the pivots are not all 1")  
        return(False)  
    else:  
        r = erank(A)  
        #print(f"r is {r} and f is {f}")  
        for i in range(1,r):  
            for j in range(i):  
                #print(f"i is {i} and j is {j} and f[i+1] is {f[i+1]} and the  
                ↪ [j,f[i+1]] entry is {A[j,f[i+1]]}")  
                if A[j,f[i+1]] != 0:  
                    return(False)  
    return(True)
```

```
[27]: def erank(A):  
    r"""  
    This returns the rank of a matrix in echelon form  
    """  
    f = fnz(A)  
    if finccheck(f) == True:  
        r = max([i for i in range(len(f)) if f[i] != None])  
        return(r)  
    else:  
        print("A is not in echelon form, first apply step one")
```

```
[28]: fnz(A)
```

```
[28]: [-1, 0, 0, 0, 2]
```

```
[29]: finccheck(fnz(A))
```

```
[29]: False
```

```
[30]: finccheck([-1,3,6,9,None,None])
```

[30]: True

```
[31]: finccheck([-1,3,6,9,9,12])
```

[31]: False

```
[32]: ifionecheck(B0)
```

[32]: False

```
[33]: ifionecheck(C0)
```

[33]: True

```
[34]: erank(A)
```

A is not in echelon form, first apply step one

```
[35]: erank(B0)
```

[35]: 3

4 Factoring steps

```
[36]: def stepone(A, slist=[]):
    r"""
    Iterates step one to produce an echelon matrix and an slist
    The slist should default to [] if not specified in the call
    """

    t=A.nrows()
    s=A.ncols()
    f = fnz(A)
    #print(f"the increasing sequence is{f}")
    if finccheck(f):
        #print("the output matrix is now in echelon form, execute steptwo")
        return(A,slist)
    else:
        m = min([f[k] for k in range(1, len(f)) if f[k] != None and
↪ (f[k-1]==None or f[k-1]>=f[k])])
        #print(f"the min column with a pivot is {m}")
        i= max([j for j in range(1, len(f)) if f[j]==m])
        #print(f"the max row with a pivot in column {m} is {i}")
        c = A[i-2,f[i]] / A[i-1,f[i]]
        B = sinv(i-1,c,t) * A
        slist.append([i-1,c])
        #print(f"B is {B} and slist is {slist}")
        return(stepone(B, slist))
```

```
[37]: def steptwo(B):
    r"""
    This takes the matrix B and makes the pivots all 1.
    The output is the new matrix and the hlist
    """

    t=B.nrows()
    s=B.ncols()
    f = fnz(B)
    if finccheck(f):
        hlist=[]
        for i in range(1,len(f)):
            if f[i] == None:
                B=B
                hlist.append(1)
            else:
                hlist.append(B[i-1,f[i]])
                B = hgen(i,1/B[i-1,f[i]],t) * B
        return(B,hlist)
    else:
        print("A is not in echelon form, execute step one")
```

```

[38]: def stepthree(C):
    t=C.nrows()
    s=C.ncols()
    f = fnz(C)
    if finccheck(f):
        if ifionecheck(C):
            #print(f)
            r = max([k for k in range(1,len(f)) if f[k]!=None])
            xlist = []
            for i in range(r,1,-1):
                #print(f"r and i and f[i] are {r} and {i} and {f[i]}")
                for j in range(i-1,0,-1):
                    #print(f"j and f[i] {j} and {f[i]}")
                    #print(f"calling xgen({j},{i},{C[j-1,f[i]]},{t})")
                    if C[j-1,f[i]] != 0:
                        xlist.append([j,i,C[j-1,f[i]]])
                        C = xgen(j,i,-C[j-1,f[i]],t) * C
            return(C,xlist)
        else:
            print("A is in echelon form but pivots are not all 1, execute_
↪steptwo")
    else:
        print("A is not in echelon form, execute stepone")

```

```

[39]: def stepfour(R):
    t=R.nrows()
    s=R.ncols()
    f = fnz(R)
    if finccheck(f):
        if ifionecheck(R):
            if xredcheck(R):
                #print(f)
                r = erank(R)
                rxlist = []
                for i in range(1,r+1):
                    for j in range(f[i]+2,s+1):
                        #print(f"rmult by xgen({f[i]+1},{j},{-R[i-1,j-1]},{s})")
                        if R[i-1,j-1] != 0:
                            #This next line was getting the list in the wrong_
↪order

                            #rxlist.append([f[i]+1,j,R[i-1,j-1]])
                            #Lets prepend instead
                            rxlist.insert(0,[f[i]+1,j,R[i-1,j-1]])
                            R = R * xgen(f[i]+1,j,-R[i-1,j-1],s)
                            #print(f"new R is {R}")
                return(R,rxlist)
            else:

```



```

        print("A is in echelon form with pivots all 1 but is not_
↪reduced, execute stepthree")
    else:
        print("A is in echelon form but pivots are not all 1, execute_
↪steptwo")
    else:
        print("A is not in echelon form, execute stepone")

```

```

[40]: def stepfive(L):
    t = L.nrows()
    s = L.ncols()
    f = fnz(L)
    if finccheck(f):
        if ifonecheck(L):
            if xredcheck(L):
                r = erank(L)
                #print(f"r is {r}")
                rslist = []
                for i in range(1,r+1):
                    #print(f"i-1 is {i-1} and f[i] is {f[i]} and f[i]>i-1 is_
↪{f[i]>i-1}")
                    if f[i]>i-1:
                        for j in range(f[i]+1,i,-1):
                            #print(f"j is {j}")
                            L = L * sgen(j-1,0,s)
                            #print(f"the new L is {L}")
                            #This next line was getting the list in the wrong_
↪order
                            #rslist.append([j-1,0])
                            #Lets prepend instead
                            rslist.insert(0,[j-1,0])
                        #
                    else:
                        #
                        print("Go on please")
                return(L,rslist)
            else:
                print("A is in echelon form with pivots all 1 but is not_
↪reduced, execute stepthree")
        else:
            print("A is in echelon form but pivots are not all 1, execute_
↪steptwo")
        else:
            print("A is not in echelon form, execute stepone")

```

```

[49]: def computePQfact(A):
    r"""
    Combine steponeiter, steptwo and stepthree to produce
    the factorization  $A = P1_rQ$ 

```

```

"""
t = A.nrows()
s = A.ncols()
B=stepone(A,[])
C=steptwo(B[(0)])
D=stepthree(C[0])
R=stepfour(D[0])
F=stepfive(R[0])
slist = B[1]
slen = len(slist)
S =identity_matrix(QQ, t)
for i in range(slen):
    sfactor = slist[i]
    S = S*sgen(sfactor[0],sfactor[1],t)
hlist = C[1]
hlen = len(hlist)
H =identity_matrix(QQ, t)
for i in range(hlen):
    hfactor = hlist[i]
    H = H*hgen(i+1,hfactor,t)
xlist = D[1]
xlen = len(xlist)
X =identity_matrix(QQ, t)
for i in range(xlen):
    xfactor = xlist[i]
    X = X*xgen(xfactor[0],xfactor[1],xfactor[2],t)
P = S*H*X
rxlist = R[1]
#print(f"rxlist is {rxlist}")
rxlen = len(rxlist)
RX =identity_matrix(QQ, s)
for i in range(rxlen):
    rxfactor = rxlist[i]
    #print(f"i is {i} and rxfactor is {rxfactor}")
    RX = xgen(rxfactor[0],rxfactor[1],rxfactor[2],s)*RX
rslist = F[1]
rslen = len(rslist)
RS =identity_matrix(QQ, s)
for i in range(rslen):
    rsfactor = rslist[i]
    RS = RS*sgen(rsfactor[0],rsfactor[1],s)
Q=RS*RX
#checkone = S*B[0]
#print("checkone: S*B[0] is")
#print(f"{checkone}")
#checktwo = H*C[0]
#print("checktwo: H*C[0] is")

```

```

#print(f"{checktwo}")
#checkthree = X*D[0]
#print("checkthree: X*D[0] is")
#print(f"{checkthree}")
#checkfour = R[0]*RX
#print(f"checkfour: R[0]*RX is {checkfour}")
#P=S*H*X
#checkfive = P*D[0]
#print("checkfive: P*D[0] is")
#print(f"{checkfive}")
#checksix = F[0]*RS
#print("checksix: F[0]*RS is")
#print(f"{checksix}")
#checkseven = F[0]*Q
#print("checkseven: F[0]*Q is")
#print(f"{checkseven}")
print("Computing the factorization of A=")
print(f"{A}")
print(f"The s(i,c,{t}) factors are {slist}")
print(f"The h(i,c,{t}) factors are {hlist}")
print(f"The x(i,j,c,{t}) factors are {xlist}")
print(f"The right s(i,0,{s}) factors are {rslist}")
print(f"The right x(i,j,c,{s}) factors are {rxlist}")
print(f"The left orbit representative in reduced row echelon form is R=")
print(f"{D[0]}")
print(f"The rank of A is r={erank(D[0])}")
checkeight = P*F[0]*Q
print("check: P*F[0]*Q is")
print(f"{checkeight}")
print("A,P,1_r and Q are")
return(A,P,F[0],Q)

```

[50]: computePQfact(A)

```

Computing the factorization of A=
[  -3   -36   -39   -42   -46   -84]
[  -9  -108 -233/2  -114 -247/2  -167]
[   3    36    39    42    45    48]
[   0     0    1/4     6   25/4   13/2]
The s(i,c,4) factors are [[2, -3], [1, -1], [3, 2], [2, 0], [3, 1]]
The h(i,c,4) factors are [3, 1/4, -1, 1]
The x(i,j,c,4) factors are [[2, 3, 25], [1, 3, 15], [1, 2, 13]]
The right s(i,0,6) factors are [[3, 0], [4, 0], [2, 0]]
The right x(i,j,c,6) factors are [[5, 6, 36], [3, 6, -874], [3, 4, 24], [1, 6,
10838], [1, 4, -298], [1, 2, 12]]
The left orbit representative in reduced row echelon form is R=
[   1   12    0 -298    0 10838]
[   0    0    1   24    0 -874]

```

```
[ 0 0 0 0 1 36]
[ 0 0 0 0 0 0]
```

The rank of A is r=3

check: $P \cdot F[0] \cdot Q$ is

```
[ -3 -36 -39 -42 -46 -84]
[ -9 -108 -233/2 -114 -247/2 -167]
[ 3 36 39 42 45 48]
[ 0 0 1/4 6 25/4 13/2]
```

A, P, I_r and Q are

```
[50]: (
[ -3 -36 -39 -42 -46 -84]
[ -9 -108 -233/2 -114 -247/2 -167]
[ 3 36 39 42 45 48]
[ 0 0 1/4 6 25/4 13/2],

[ -3 -39 -46 1] [1 0 0 0 0 0]
[ -9 -233/2 -247/2 0] [0 1 0 0 0 0]
[ 3 39 45 0] [0 0 1 0 0 0]
[ 0 1/4 25/4 0], [0 0 0 0 0 0],

[ 1 12 0 -298 0 10838]
[ 0 0 1 24 0 -874]
[ 0 0 0 0 1 36]
[ 0 1 0 0 0 0]
[ 0 0 0 1 0 0]
[ 0 0 0 0 0 1]
)
```

```
[ ]:
```