

Coordinates

21.01.2026 (1)
Linear Algebra
Lect 16 A. Ramm

V a vector space

$B = \{b_1, b_2, \dots, b_n\}$ a basis of V .

$v \in V$.

The coordinate vector of v with respect to the basis B is

$$[v]_B = \begin{pmatrix} c_1 \\ c_2 \\ \vdots \\ c_n \end{pmatrix} \text{ if } v = c_1 b_1 + c_2 b_2 + \dots + c_n b_n$$

Example V34 Vector space: $\mathbb{Q}[x]_{\leq 2}$.

Basis of $\mathbb{Q}[x]_{\leq 2}$: $B = \{1, x, x^2\}$

$$B = \left\{ 2, \frac{1}{2}x, -3x^2 \right\}$$

Vector: $p = 2 + 7x - 9x^2$.

$$[p]_B = \begin{pmatrix} 2 \\ 7 \\ 9 \end{pmatrix} \text{ since } 2 + 7x - 9x^2 = 2 \cdot 1 + 7x - 9x^2$$

$$[p]_B = \begin{pmatrix} 1 \\ 14 \\ 3 \end{pmatrix} \text{ since } 2 + 7x - 9x^2 = 1 \cdot 2 + 14 \cdot \frac{1}{2}x + 3 \cdot (-3x^2)$$

Example V33 Vector space: $\mathbb{R}^2$

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Linear Algebra

Lect. 16 A. Rem

Bases of $\mathbb{R}^2$: $S = \{ (1,0), (0,1) \}$

$B = \{ (2,1), (-1,1) \}$

Vector: $v = (1,5)$

$$[v]_S = \begin{pmatrix} 1 \\ 5 \end{pmatrix} \text{ since } (1,5) = 1 \cdot (1,0) + 5 \cdot (0,1)$$

$$[v]_B = \begin{pmatrix} 2 \\ 3 \end{pmatrix} \text{ since } (1,5) = 2 \cdot (2,1) + 3 \cdot (-1,1)$$

$T: V \rightarrow W$ a linear transformation.

$B = \{b_1, \dots, b_s\}$ a basis of V .

$D = \{d_1, \dots, d_t\}$ a basis of W .

The matrix of T with respect to the basis B and the basis D is

$$[T]_{DB} = \begin{pmatrix} a_{11} & \dots & a_{1s} \\ a_{21} & \dots & a_{2s} \\ \vdots & & \vdots \\ a_{t1} & \dots & a_{ts} \end{pmatrix} \quad \text{if}$$

$$T(b_1) = a_{11}d_1 + a_{21}d_2 + \dots + a_{t1}d_t,$$

$$T(b_2) = a_{12}d_1 + a_{22}d_2 + \dots + a_{t2}d_t,$$

$\vdots$

$$T(b_s) = a_{1s}d_1 + a_{2s}d_2 + \dots + a_{ts}d_t.$$

Example LT 2 and 14

21.01.2016 (3)

Linear Algebra

Linear transformation: $\mathbb{R}[x]_{\leq 3} \rightarrow \mathbb{R}[x]_{\leq 2}$ Let T be. A. Ram

given by

$$T(a_0 + a_1x + a_2x^2 + a_3x^3) = a_1 + 2a_2x + 3a_3x^2$$

$S = \{1, x, x^2, x^3\}$ is a basis of $\mathbb{R}[x]_{\leq 3}$.

$B = \{1, x, x^2\}$ is a basis of $\mathbb{R}[x]_{\leq 2}$.

$$[T]_{BS} = \begin{pmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 3 \end{pmatrix} \quad \text{since}$$

$$T(1) = 0 = 0 + 0x + 0x^2,$$

$$T(x) = 1 = 1 + 0x + 0x^2,$$

$$T(x^2) = 2x = 0 + 2x + 0x^2,$$

$$T(x^3) = 3x^2 = 0 + 0x + 3x^2.$$

Example LT 11 Linear transformation $T: M_{\mathbb{R}}(\mathbb{R}) \rightarrow M_{\mathbb{R}}(\mathbb{R})$

given by

$T(Q) = Q^t$, where Q^t is the transpose of the matrix Q .

$S = \{E_{11}, E_{12}, E_{21}, E_{22}\}$ is a basis of $M_{\mathbb{R}}(\mathbb{R})$.

$$[T]_{SS} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \quad \text{since}$$

$$T(E_{11}) = E_{11} = E_{11} + 0E_{12} + 0E_{21} + 0E_{22}, \text{ Lect. 10 A. Ram}$$

$$T(E_{12}) = E_{12} = 0E_{11} + 0E_{12} + 1 \cdot E_{21} + 0E_{22},$$

$$T(E_{21}) = E_{12} = 0E_{11} + 1 \cdot E_{12} + 0 \cdot E_{21} + 0E_{22},$$

$$T(E_{22}) = E_{22} = 0E_{11} + 0E_{12} + 0E_{21} + 1 \cdot E_{22}.$$

V a vector space.

$B = \{b_1, \dots, b_n\}$ a basis of V

$D = \{d_1, \dots, d_n\}$ another basis of V .

The change of basis matrix from the basis B to the basis D is

$$[I]_{DB} = \begin{pmatrix} a_{11} & \dots & a_{1n} \\ a_{21} & & a_{2n} \\ \vdots & & \vdots \\ a_{n1} & \dots & a_{nn} \end{pmatrix} \quad \text{if}$$

$$b_1 = a_{11}d_1 + a_{21}d_2 + \dots + a_{n1}d_n$$

$$b_2 = a_{12}d_1 + a_{22}d_2 + \dots + a_{n2}d_n$$

$$\vdots$$

$$b_n = a_{1n}d_1 + a_{2n}d_2 + \dots + a_{nn}d_n.$$

Let

$$T: U \rightarrow V \text{ and } f: V \rightarrow W$$

be linear transformations. Let

$$B = \{u_1, \dots, u_k\} \text{ be a basis of } U,$$

$$C = \{v_1, \dots, v_s\} \text{ a basis of } V,$$

$$D = \{w_1, \dots, w_t\} \text{ a basis of } W.$$

Then $(f \circ T): U \rightarrow W$ and

$$[f \circ T]_{DB} = [f]_{DC} [T]_{CB}.$$

Let V be a vector space and let

$$I: V \rightarrow V \text{ given by } I(v) = v,$$

be the identity transformation. Let

$$B = \{v_1, \dots, v_n\} \text{ be a basis of } V,$$

$$S = \{e_1, \dots, e_n\} \text{ be another basis of } V.$$

Then

$$[I]_{BB} = 1, \quad [I]_{SS} = 1, \quad [I]_{SB} [I]_{BS} = [I]_{SS} = 1$$

$$\text{and } [I]_{SB} = [I]_{BS}^{-1}.$$