

GTLA Lecture 10.09.2020

A choice of generators and relations for S_3

$$S_3 = \{ \equiv, \times, \overline{\times}, \underline{\times}, \overline{\overline{\times}}, \times \}$$

$$\text{Let } = \{ 1, r, r^2, sr, sr^2, s \}$$

$$1 = \overleftarrow{\equiv} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$r = \overleftarrow{\times} = \begin{pmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix}$$

$$s = \overleftarrow{\overline{\times}} = \begin{pmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{pmatrix}$$

$$\begin{aligned} r^2 &= \overleftarrow{\overline{\overline{\times}}} = \overleftarrow{\times} & r^3 &= r^2 \cdot r = \overleftarrow{\overline{\overline{\times}}} \overleftarrow{\times} = \overleftarrow{\equiv} \\ & & &= 1. \end{aligned}$$

$$s^2 = \overleftarrow{\overline{\overline{\overline{\times}}}} = \overleftarrow{\equiv} = 1.$$

$$sr = \overleftarrow{\overline{\overline{\times}}} \overleftarrow{\times} = \overleftarrow{\underline{\times}}$$

$$sr^2 = \overleftarrow{\overline{\overline{\times}}} \overleftarrow{\overline{\overline{\times}}} = \overleftarrow{\overline{\times}}$$

$$\begin{aligned} rs &= \overleftarrow{\times} \overleftarrow{\overline{\overline{\times}}} = \overleftarrow{\overline{\times}} \\ &= sr^2 \end{aligned}$$

Note: $r^2 = r^{-1}$ since $r^3 = 1$.

$r \cdot r^2 = r^3 = 1$ So $r^2 = r^{-1}$.

$$S_3 = \{1, r, r^2, s, sr, sr^2\}$$

is generated by r and s
with relations

$$s^2 = 1, \quad r^3 = 1, \quad rs = sr^2 = sr^{-1}$$

Let G be a group, S a set.

An action of G on S is a function

$$G \times S \longrightarrow S \\ (g, x) \longmapsto g \cdot x \quad \text{such that}$$

(a) If $g_1, g_2 \in G$ and $x \in S$

$$g_1 \cdot (g_2 \cdot x) = (g_1 g_2) \cdot x.$$

(b) If $x \in S$ then $1 \cdot x = x$

S (with its action of G) is a
 G -set (analogous to an
 \mathbb{F} -vector space)

Let S be a G -set. Let $x \in S$.

The stabiliser of x is

$$\text{Stab}_G(x) = \{g \in G \mid g \cdot x = x\}$$

The orbit of x is

$$G \cdot x = \{g \cdot x \mid g \in G\}$$

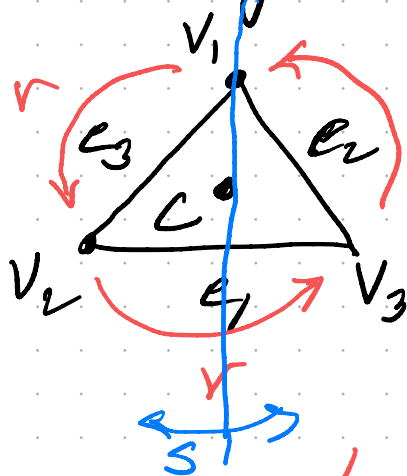
Analogy:

Let $f: G \rightarrow H$ be a homomorphism.

$$\ker f = \{g \in G \mid f(g) = 1\}$$

$$\text{im } f = \{f(g) \mid g \in G\}$$

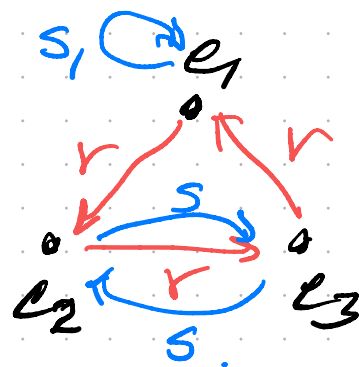
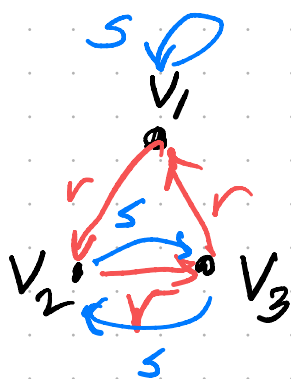
Example $G = S_3 = \{1, r, r^2, s, sr, sr^2\}$
acting on a triangle.



$$S = \{c, v_1, v_2, v_3, e_1, e_2, e_3\}$$

r is rotation by $\frac{2\pi}{3}$.

s is reflection on vertical axis.



Orbits $G = S_3$ $S = \{C, v_1, v_2, v_3, e_1, e_2, e_3\}$

$$G \cdot C = \{C\}$$

$$G \cdot e_1 = \{e_1, e_2, e_3\}$$

$$G \cdot v_1 = \{v_1, v_2, v_3\}$$

$$= G \cdot e_2$$

$$= G \cdot v_2 = \{v_2, v_1, v_3\}$$

$$= G \cdot e_3$$

$$= G \cdot v_3 = \{v_3, v_1, v_2\}$$

Stabilizers

$$\text{Stab}_G(C) = \{1, r, r^2, s, sr, sr^2\}$$

$$\text{Stab}_G(v_1) = \{1, s\}$$

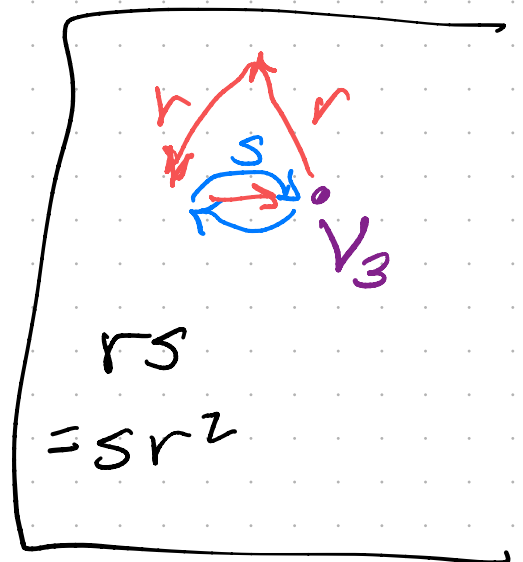
$$\text{Stab}_G(v_2) = \{1, sr\}$$

$$\text{Stab}_G(v_3) = \{1, sr^2\}$$

$$\text{Stab}_G(e_1) = \{1, s\}$$

$$\text{Stab}_G(e_2) = \{1, sr\}$$

$$\text{Stab}_G(e_3) = \{1, sr^2\}$$



Proposition Let G be a group and let S be a G -set. Let $x \in S$ and $g \in G$.

(a) $G \cdot x$ is a subset of S

(b) $\text{Stab}_G(x)$ is a subgroup of G .

(c) $\text{Stab}_G(g \cdot x) = g \text{Stab}_G(x) g^{-1}$!

(d) The orbits partition S .
 $\text{Stab}_G(g^{-1} \cdot x) = g^{-1} \text{Stab}_G(x) g$.

Proof (d)

To show: (da) $\bigcup_{x \in S} G \cdot x = S$.

(db) If $x, y \in S$ and $G \cdot x \cap G \cdot y \neq \emptyset$
then $G \cdot x = G \cdot y$.

(da) To show: (daa) $\bigcup_{x \in S} G \cdot x \subseteq S$

(dab) $S \subseteq \bigcup_{x \in S} G \cdot x$.

(daa) Since $G \cdot x = \{g \cdot x \mid g \in G\} \subseteq S$
then $\bigcup_{x \in S} G \cdot x \subseteq S$.

(dab) To show: If $z \in S$ then there
exists $x \in S$ such that $z \in G \cdot x$.

Assume $z \in S$.

To show: There exists $x \in S$ such
that $z \in G \cdot x$.

Let $x = z$

Since $z = 1 \cdot z = 1 \cdot x \in G \cdot x$

then $z \in G \cdot x$.

$$\Rightarrow \bigcup_{x \in S} G \cdot x = S.$$

(db) To show: If $x, y \in S$ and $G \cdot x \cap G \cdot y \neq \emptyset$ then $G \cdot x = G \cdot y$.

Assume $x, y \in S$ and $G \cdot x \cap G \cdot y \neq \emptyset$.

Then there exists $z \in S$ such that

$$z \in G \cdot x \text{ and } z \in G \cdot y.$$

So there exist $g_1, g_2 \in G$ such that

$$z = g_1 \cdot x \text{ and } z = g_2 \cdot y.$$

$$\Rightarrow x = g_1^{-1} \cdot z = g_1^{-1} g_2 \cdot y$$

$$\text{and } y = g_2^{-1} \cdot z = g_2^{-1} g_1 \cdot x.$$

To show: $G \cdot x = G \cdot y$.

To show: (dba) $G \cdot x \subseteq G \cdot y$

(dcb) $G \cdot y \subseteq G \cdot x$.

(dba) To show: If $a \in G \cdot x$ then $a \in G \cdot y$.

Assume $a \in G \cdot x$.

To show: $a \in G \cdot y$.

Since $a \in G \cdot x$ then there exists $g \in G$ such that $a = g \cdot x$.

So $a = g \cdot x = g \cdot g_1^{-1} g_2 \cdot y \in G \cdot y$.

So $G \cdot x \subseteq G \cdot y$.

(d) To show: If $b \in G \cdot y$ then $b \in G \cdot x$.

Let $b \in G \cdot y$. Then there exists $k \in G$ such that $b = k \cdot y$.

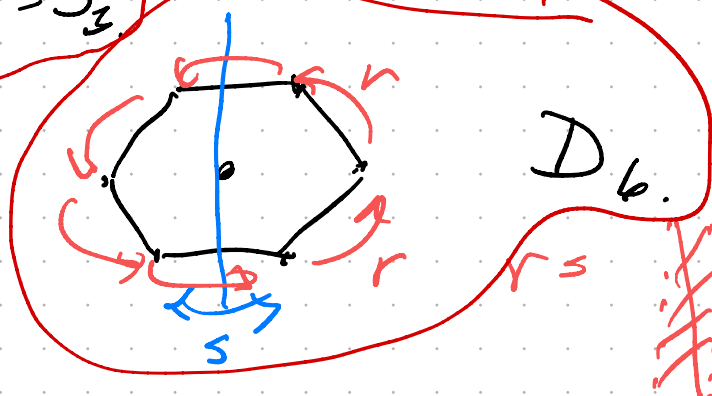
So $b = k \cdot y = k \cdot g_2^{-1} g_1 \cdot x = (k g_2^{-1} g_1) \cdot x$

So $G \cdot y \subseteq G \cdot x$.

So $G \cdot x = G \cdot y$.

So the orbits partition S . \square

$\Delta D_1 = S_3$



$S_6 \cong D_6$

~~$S =$~~