

Calculus 2 Last Lecture

25.10.2019

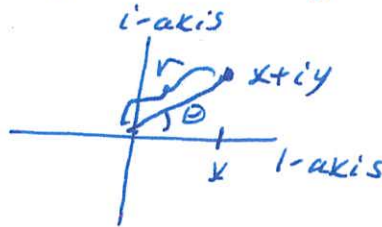
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A. Rome

Complex numbers:

$$i^2 = -1, \quad \overline{x+iy} = x-iy, \quad |x+iy| = \sqrt{x^2+y^2}$$

$$x+iy = re^{i\theta}$$



with $r = \sqrt{x^2+y^2}$

$$x = r \cos \theta$$

$$\tan \theta = \frac{y}{x}$$

$$y = r \sin \theta$$

Trig and hyperbolic functions

$$\sin x = \frac{1}{2i} (e^{ix} - e^{-ix})$$

$$\cos x = \frac{1}{2} (e^{ix} + e^{-ix})$$

$$\sinh x = \frac{1}{2} (e^x - e^{-x})$$

$$\cosh x = \frac{1}{2} (e^x + e^{-x})$$

$$e^{ix} = \cos x + i \sin x$$

$$e^x = \sinh x + \cosh x$$

$$\cos^2 x + \sin^2 x = 1$$

$$\cosh^2 x - \sinh^2 x = 1$$

Limits, sequences, series

$L = \lim_{x \rightarrow a} f(x)$ means $f(x)$ gets closer and closer to L as x gets closer and closer to a

$$\frac{1}{1-s} = 1 + s + s^2 + s^3 + \dots \quad (\text{geometric series})$$

$$e^s = 1 + s + \frac{1}{2} s^2 + \frac{1}{3!} s^3 + \frac{1}{4!} s^4 + \dots \quad (\text{exponential series})$$

$$S(s) = 1 + \frac{1}{2^s} + \frac{1}{3^s} + \frac{1}{4^s} + \dots \quad \left(\begin{array}{l} \text{harmonic series } S(1) \\ p\text{-series } S(p) \text{ for } p \in \mathbb{R}, p > 0 \\ \text{Riemann zeta function} \end{array} \right)$$

Continuity The function f is continuous if f is continuous

$$\lim_{x \rightarrow a} f(g) = f(\lim_{x \rightarrow a} g)$$

and $f(x) = x^n$ and $f(x) = e^x$ are continuous.

Differentiation and Integration $\int \frac{df}{dx} dx = f$

$$\frac{d(cf)}{dx} = c \frac{df}{dx}$$

$$\int (cg) dx = c \int g dx$$

$$\frac{d(f+g)}{dx} = \frac{df}{dx} + \frac{dg}{dx}$$

$$\int (f+g) dx = \int f dx + \int g dx$$

$$\frac{d(uv)}{dx} = u \frac{dv}{dx} + \frac{du}{dx} v$$

$$\int u dv = uv - \int v du$$

$$\frac{d(f \circ u)}{dx} = \frac{df}{du} \frac{du}{dx}$$

$$\int g \frac{du}{dx} dx = \int g du$$

Fundamental theorems

$$D_f(a) = \lim_{h \rightarrow 0} \frac{f(a+h) - f(a)}{h}$$

(first principles)

$$\text{If } \frac{df}{dx} = g \text{ then } \left. \frac{df}{dx} \right|_{x=a} = g(a)$$

Fundamental theorem of change:

$$D_f(a) = \left. \frac{df}{dx} \right|_{x=a}$$

$$\int_{x=a}^{x=b} g dx = \lim_{N \rightarrow \infty} \left(g(a) \frac{1}{N} + g\left(a + \frac{1}{N}\right) \frac{1}{N} + \dots + g\left(b - \frac{1}{N}\right) \frac{1}{N} \right)$$

If $\frac{df}{dx} = g$ then let $\int g dx \Big|_{x=a}^{x=b} = f(b) - f(a)$.

Fundamental theorem of calculus:

$$\int_{x=a}^{x=b} g dx = \int g dx \Big|_{x=a}^{x=b}$$

Differential Equations

Separable: If $\frac{dy}{dx} = PQ$ then $\frac{1}{P} \frac{dy}{dx} = Q$

and $\int \frac{1}{P} dy = \int Q dx$

Integrating factors: If $Q = \frac{dy}{dx} + Py = \frac{dy}{dx} + \frac{1}{I} \frac{dI}{dx} y$

then $QI = I \frac{dy}{dx} + \frac{dI}{dx} y = \frac{d(Iy)}{dx}$

so that $\int QI dx = Iy$ and $y = \frac{1}{I} \int QI dx$

with $\log I = \int P dx$.

English to math translation:

Population models, mixing problems
springs, circuits

Derivative matrix and chain rule

$$f: \mathbb{R}^m \rightarrow \mathbb{R}^n$$

$$\begin{pmatrix} x_1 \\ \vdots \\ x_m \end{pmatrix} \mapsto \begin{pmatrix} f_1 \\ \vdots \\ f_n \end{pmatrix}$$

$$Df = \begin{pmatrix} \frac{\partial f_1}{\partial x_1} & \dots & \frac{\partial f_1}{\partial x_m} \\ \frac{\partial f_2}{\partial x_1} & \dots & \frac{\partial f_2}{\partial x_m} \\ \vdots & & \vdots \\ \frac{\partial f_n}{\partial x_1} & \dots & \frac{\partial f_n}{\partial x_m} \end{pmatrix}$$

Chain rule: $D_{f \circ u} = Df D_u$.

Functions $f: \mathbb{R}^2 \rightarrow \mathbb{R}$. Let $(x_0, y_0) \in \mathbb{R}^2$.

Gradient at (x_0, y_0) : $\vec{\nabla} f|_{(x,y)=(x_0,y_0)} = \left(\frac{\partial f}{\partial x} \Big|_{(x,y)=(x_0,y_0)}, \frac{\partial f}{\partial y} \Big|_{(x,y)=(x_0,y_0)} \right)$

Hessian at (x_0, y_0)

$$H_f = \begin{pmatrix} \frac{\partial^2 f}{\partial x^2} & \frac{\partial^2 f}{\partial x \partial y} \\ \frac{\partial^2 f}{\partial y \partial x} & \frac{\partial^2 f}{\partial y^2} \end{pmatrix} \Big|_{(x,y)=(x_0,y_0)}$$

Directional derivative in direction \hat{u} at (x_0, y_0)

$$\vec{\nabla} f|_{(x,y)=(x_0,y_0)} \cdot \hat{u}$$

Linear approximation to f at (x_0, y_0)

$$f(x,y) \approx f(x_0, y_0) + \frac{\partial f}{\partial x} \Big|_{(x,y)=(x_0,y_0)} (x-x_0) + \frac{\partial f}{\partial y} \Big|_{(x,y)=(x_0,y_0)} (y-y_0)$$

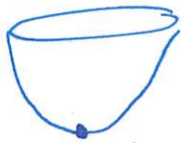
Tangent plane to f at (x_0, y_0)

$$z - z_0 = \frac{\partial f}{\partial x} \Big|_{(x,y)=(x_0,y_0)} (x-x_0) + \frac{\partial f}{\partial y} \Big|_{(x,y)=(x_0,y_0)} (y-y_0)$$

Stationary points, local minima, local maxima, and Saddle points

A stationary point is (x_0, y_0) with

$$\nabla f|_{(x,y)=(x_0,y_0)} = (0,0)$$



local minimum

$$\frac{\partial^2 f}{\partial x^2} |_{(x,y)=(x_0,y_0)} > 0$$

$$\det(H_f) > 0$$



local maximum

$$\frac{\partial^2 f}{\partial x^2} |_{(x,y)=(x_0,y_0)} < 0$$

$$\det(H_f) > 0$$



saddle point

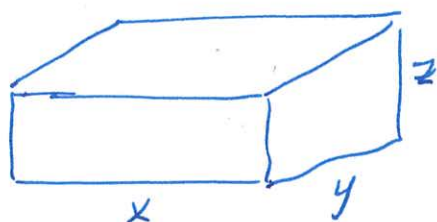
$$\det(H_f) < 0$$

Consider an open top box of

length x , width y and height z .

with volume 4. Find the minimum amount of metal to make the box.

Solution



$$\text{Volume} = xyz = 4.$$

Minimize metal, $M = 2xz + 2yz + xy$

Since $4 = xyz$ then $z = \frac{4}{xy}$.

So

$$M = 2x \frac{4}{xy} + 2y \frac{4}{xy} + xy = \frac{8}{y} + \frac{8}{x} + xy.$$

Then

$$\begin{aligned} \vec{\nabla} M &= \left(\frac{\partial M}{\partial x}, \frac{\partial M}{\partial y} \right) = \left(0 - \frac{8}{x^2} + y, -\frac{8}{y^2} + 0 + x \right) \\ &= \left(y - \frac{8}{x^2}, x - \frac{8}{y^2} \right). \end{aligned}$$

The stationary point is when

$$(0, 0) = \vec{\nabla} M = \left(y - \frac{8}{x^2}, x - \frac{8}{y^2} \right) \text{ so that}$$

$$y = \frac{8}{x^2} \text{ and } x = \frac{8}{y^2} \text{ giving } y = \frac{8}{\left(\frac{8}{y^2}\right)^2} = \frac{8y^4}{8^2}$$

$$\text{So } \frac{1}{8} y^4 - y = 0. \text{ So } y^4 - 8y = 0. \text{ So } y(y^3 - 8) = 0.$$

$$\text{So } y = 0 \text{ or } y^3 = 8. \text{ So } y = 0 \text{ or } y = 2.$$

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If $y=1$
~~then~~ $x = \frac{8}{2^2} = \frac{8}{4} = 2$ and $z = \frac{4}{xy} = \frac{4}{2 \cdot 2} = 1$

So $M = 2 \cdot 2 \cdot 1 + 2 \cdot 2 \cdot 1 + 2 \cdot 2 = \del{8} 4 + 4 + 4 = 12$

~~If $y=0$ then~~ We want $y > 0$.