

Generalized matrix algebras

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1 Generalized matrix algebras

The algebra of $n \times n$ matrices

$$M_n \quad \text{has basis} \quad \{E_{ST} \mid 1 \leq S, T \leq n\} \quad \text{with} \quad E_{ST}E_{UV} = \delta_{TU}E_{SV}. \quad (1.1)$$

Fix constants ε_{TU} , $1 \leq T, U \leq n$. The *generalized matrix algebra*

$$M_n(\varepsilon) \quad \text{has basis} \quad \{E_{ST} \mid 1 \leq S, T \leq n\} \quad \text{with} \quad E_{ST} \cdot E_{UV} = \varepsilon_{TU}E_{SV}. \quad (1.2)$$

If we view elements of $M_n(\varepsilon)$ as matrices then

$$x \cdot y = x\varepsilon y, \quad \text{for} \quad x = \sum_{S,T} x_{ST}E_{ST}, \quad y = \sum_{U,V} y_{UV}E_{UV}, \quad \text{and} \quad \varepsilon = (\varepsilon_{TU}).$$

Let A be an algebra and fix $\varepsilon \in A$. The *homotope algebra* $A(\varepsilon)$ is the algebra A with a new multiplication given by

$$x \cdot y = x\varepsilon y, \quad \text{for} \quad x, y \in A. \quad (1.3)$$

Let p, q be invertible elements of A . Then

$$\begin{array}{ccc} A(paq) & \xrightarrow{\sim} & A(a) \\ x & \mapsto & qxp \end{array} \quad \text{is an algebra isomorphism.}$$

Rewrite the construction of $M_n(\varepsilon)$: Let $L = \mathbb{F}^n$ and $R = \mathbb{F}^n$ and identify M_n with $L \otimes R$.

$$\text{Identify } \varepsilon \quad \text{with a map} \quad \begin{array}{ccc} R \otimes L & \longrightarrow & \mathbb{F} \\ v_S \otimes v_T & \longmapsto & \varepsilon_{ST} \end{array}$$

Then

$$M_n(\varepsilon) = L \otimes R \quad \text{with product} \quad (\ell_1 \otimes r_1)(\ell_2 \otimes r_2) = \ell_1 \otimes \varepsilon(r_1 \otimes \ell_2)r_2.$$

Let A be an algebra and let L be a left A -module and R a right A -module. Let

$$\varepsilon : L \otimes_{\mathbb{F}} R \longrightarrow A, \quad \text{be an } (A, A)\text{-bimodule homomorphism.} \quad (1.4)$$

The *basic construction* is the algebra

$$A(\varepsilon) = R \otimes_A L \quad \text{with} \quad (r_1 \otimes \ell_1)(r_2 \otimes \ell_2) = r_1 \otimes \varepsilon(\ell_1 \otimes r_2)\ell_2, \quad (1.5)$$

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for $r_1, r_2 \in R$ and $\ell_1, \ell_2 \in L$.

One case which is used often is when $A \subseteq B$ is an inclusion of algebras with a given (A, A) bimodule homomorphism $\varepsilon_1: B \rightarrow A$, where A acts by left and right multiplication on B (and on A). Then

$$\begin{aligned} \varepsilon: B \otimes_{\mathbb{F}} B &\longrightarrow A \\ b_1 \otimes b_2 &\longmapsto \varepsilon_1(b_1 b_2) \end{aligned} \quad (1.6)$$

is an (A, A) bimodule homomorphism and

$$A(\varepsilon) = B \otimes_A B \quad \text{with} \quad (b_1 \otimes b_2)(b_3 \otimes b_4) = b_1 \otimes \varepsilon(b_2 \otimes b_3)b_4, \quad (1.7)$$

for $b_1, b_2, b_3, b_4 \in B$.

The algebra $A(\varepsilon)$ does not usually have an identity. Let C and D be rings,

$$\begin{aligned} L, & \text{ a } (C, D) \text{ bimodule,} \\ R, & \text{ a } (D, C) \text{ bimodule} \end{aligned} \quad \text{and} \quad \varepsilon: L \otimes_D R \rightarrow C,$$

a (C, C) bimodule homomorphism. Define an algebra

$$A = C \oplus D \oplus L \oplus R \oplus R \otimes_C L \quad (1.8)$$

and product determined by the multiplication in C and D , the module structure of R and L and the additional relations

$$cr = 0, \quad d\ell = 0, \quad rd = 0, \quad \ell c = 0, \quad \text{and} \quad (r_1 \otimes \ell_1)(r_2 \otimes \ell_2) = r_1 \otimes \varepsilon(\ell_1 \otimes r_2)\ell_2. \quad (1.9)$$

for $r, r_1, r_2 \in R$, $\ell, \ell_1, \ell_2 \in L$, $c \in C$ and $d \in D$. Let e_C be the image of the identity of C in A and e_D the image of the identity of D in A . Then

$$1 = e_C + e_D, \quad \text{and if} \quad \begin{aligned} C &= e_C A e_C, & L &= e_C A e_D, \\ R &= e_D A e_C, & D' &= e_D A e_D, \end{aligned}$$

then

$$A = \left\{ \begin{pmatrix} c & \ell \\ r & d' \end{pmatrix} \mid c \in C, \ell \in L, r \in R, d' \in D' \right\}$$

with matrix multiplication. Then

$$\begin{aligned} e_D A e_D &= D + R \otimes_C L & \text{is a subring of } A, & \quad \text{and} \\ e_D A e_C A e_D &= R \otimes_C L & \text{is an ideal in } e_D A e_D. & \end{aligned}$$

1.1 The module category of $Z(\varepsilon)$

Let \mathcal{C} and \mathcal{D} be categories

$$F: \mathcal{C} \rightarrow \mathcal{D} \quad \text{and} \quad G: \mathcal{C} \rightarrow \mathcal{D} \quad \text{be functors,} \quad \text{and} \quad F \xrightarrow{\varepsilon} G,$$

a natural transformation. Define a category \mathcal{A} with

Objects: $(M, V; \text{PICTURE})$, where $M \in \mathcal{C}$, $V \in \mathcal{D}$, and $m, n \in \text{Mor}(\mathcal{D})$,

Morphisms: (f, g) with $f \in \text{Mor}(\mathcal{C})$, $g \in \text{Mor}(\mathcal{D})$ such that

$$\text{PICTURE} \quad \text{commutes.}$$

A fundamental case is when \mathcal{D} is the category of vector spaces over \mathbb{F} .

The equivalence between the category \mathcal{A} and the module category of $Z(\varepsilon)$ is given by letting $\mathcal{C} = C\text{-mod}$ and $\mathcal{D} = D\text{-mod}$ and

$$F: \begin{array}{ccc} \mathcal{C} & \longrightarrow & \mathcal{D} \\ M & \longmapsto & R \otimes_C M \end{array} \quad \text{and} \quad G: \begin{array}{ccc} \mathcal{C} & \longrightarrow & \mathcal{D} \\ M & \longmapsto & \text{Hom}_C(L, M) \end{array}$$

where the D -action on $\text{Hom}_C(L, M)$ is given by

$$(d\phi)(\ell) = \phi(\ell d), \quad \text{for } d \in D, \ell \in L, \text{ and } \phi \in \text{Hom}_C(L, M).$$

Then let $\varepsilon: F \rightarrow G$ be the natural transformation given by

$$\varepsilon: \begin{array}{ccc} F & \longrightarrow & G \\ R \otimes_C M & \xrightarrow{\varepsilon_M} & \text{Hom}_C(L, M) \\ r \otimes m & \longmapsto & \tau: \begin{array}{ccc} L & \rightarrow & M \\ \ell & \mapsto & \varepsilon(\ell \otimes r)m \end{array} \end{array}$$

Then

$$\begin{array}{ccc} \mathcal{A} & \xrightarrow{\sim} & A\text{-mod} \\ (X, Y, \rho, \lambda) & \leftrightarrow & M \end{array} \quad \text{where} \quad X = eM, \quad Y = (1 - e)M,$$

and the L -action and R -action on M define ρ and λ via

$$\ell y = (\lambda(y))(\ell) \quad \text{and} \quad rx = \rho(r \otimes x), \quad \text{for } \ell \in L, r \in R, x \in X \text{ and } y \in Y.$$

Note that

$$\ell x = 0 \quad \text{and} \quad ry = 0, \quad \text{for } \ell \in L, r \in R, x \in X, y \in Y,$$

and

PICTURE

commutes.

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