

4.5 Matrix groups: Some proofs

4.5.1 The presentation theorem for S_n

Proposition 4.5. *The symmetric group S_n is presented by generators s_1, s_2, \dots, s_{n-1} and relations*

$$s_i^2 = 1 \quad \text{and} \quad s_j s_{j+1} s_j = s_{j+1} s_j s_{j+1} \quad \text{and} \quad s_k s_\ell = s_\ell s_k, \quad (4.8)$$

for $i, j, k, \ell \in \{1, \dots, n-1\}$ with $j \neq n-1$ and $k \neq \ell \pm 1$.

Proof.

Generators A: the set of permutation matrices.

Relations A: all products of permutations $w_1 w_2$ given by matrix multiplication.

Generators B: s_1, \dots, s_{n-1} .

Relations B: As given in (4.8).

The proof is accomplished in four steps:

- (1) Write generators B in terms of generators A.
- (2) Deduce relations B from relations A.
- (3) Write generators A in terms of generators B.
- (4) Deduce relations A from relations B.

Step 1: Generators B in terms of generators A. This is provided by (4.1).

Step 2: Relations B from relations A. This step is given the following matrix computations:

$$s_1^2 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$s_1 s_2 s_1 = \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{pmatrix}$$

and

$$s_2 s_1 s_2 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{pmatrix}$$

so that $s_1 s_2 s_1 = s_2 s_1 s_2$ and

$$s_1 s_3 = \begin{pmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{pmatrix}$$

and

$$s_3 s_1 = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{pmatrix}$$

so that $s_1 s_3 = s_3 s_1$.

Step 3: Generators A in terms of generators B.

Let $w \in S_n$.

Let $j_1 \in \{1, \dots, n\}$ be such that $w(j_1, 1) = 1$ and let $w^{(1)} = s_1 s_2 \cdots s_{j_1-1} w$.
 Let $j_2 \in \{2, \dots, n\}$ be such that $w^{(1)}(j_2, 2) = 1$ and let $w^{(2)} = s_2 s_3 \cdots s_{j_2-1}$.
 Continue this process to obtain

$$\cdots (s_2 s_3 \cdots s_{j_2-1})(s_1 s_2 \cdots s_{j_1-1})w = 1.$$

Thus

$$w = (s_{j_1-1} \cdots s_2 s_1)(s_{j_2-1} \cdots s_3 s_2) \cdots .$$

The expression for w is a reduced word for w and a subword of the reduced word of the longest element given by

$$(s_{n-1} \cdots s_2 s_1)(s_{n-1} \cdots s_3 s_2) \cdots (s_{n-1} s_{n-2}) s_{n-1} = w_0.$$

Step 4: Relations A from relations B.

$$\begin{aligned} s_i(s_{j-1} \cdots s_2 s_1) &= s_{j-1} \cdots s_{i+2} s_i s_{i+1} s_i s_{i-1} \cdots s_2 s_1, && \text{by the third set of relations in (4.8),} \\ &= s_{j-1} \cdots s_{i+2} s_{i+1} s_i s_{i+1} s_{i-1} \cdots s_2 s_1, && \text{by the second set of relations in (4.8),} \\ &= (s_{j-1} \cdots s_{i+2} s_{i+1} s_i s_{i-1} \cdots s_2 s_1) s_i, && \text{by the third set of relations in (4.8),} \end{aligned}$$

So $s_i w$ can be written in normal form. By Step 3, w_1 can be written as a product of simple transpositions, so one simple transposition at a time, $w_1 w$ can be written in normal form. \square

If

$$w = \begin{pmatrix} 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{pmatrix} \quad \text{then} \quad s_3(s_2 s_3)(s_1 s_2 w) = s_3(s_2 s_3) \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \end{pmatrix} = s_3 \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{pmatrix} = 1,$$

so that $w = (s_2 s_1)(s_3 s_2) s_3$.

4.5.2 The presentation theorem for $GL_n(\mathbb{F})$

Theorem 4.6. *The group $GL_n(\mathbb{F})$ is presented by generators*

$$y_i(c), \quad h_j(d), \quad x_{kl}(c), \quad \text{for} \quad \begin{aligned} &c \in \mathbb{F}, d_1, \dots, d_n \in \mathbb{F}^\times, \\ &i \in \{1, \dots, n-1\}, j \in \{1, \dots, n\} \\ &k, \ell \in \{1, \dots, n\} \text{ with } k < \ell. \end{aligned}$$

with the following relations:

- The reflection relation is

$$y_i(c_1) y_i(c_2) = \begin{cases} y_i(c_1 + c_2^{-1}) h_i(c_2) h_{i+1}(-c_2^{-1}) x_{i,i+1}(c_2^{-1}), & \text{if } c_2 \neq 0, \\ x_{i,i+1}(c_1), & \text{if } c_2 = 0. \end{cases} \quad (4.9)$$

- The building relation is

$$y_i(c_1) y_{i+1}(c_2) y_i(c_3) = y_{i+1}(c_3) y_i(c_1 c_3 + c_2) y_{i+1}(c_1). \quad (4.10)$$

- The x-interchange relations are

$$\begin{aligned} x_{ij}(c_1)x_{ij}(c_2) &= x_{ij}(c_1 + c_2), \\ x_{ij}(c_1)x_{ik}(c_2) &= x_{ik}(c_2)x_{ij}(c_1), & x_{ik}(c_1)x_{jk}(c_2) &= x_{jk}(c_2)x_{ik}(c_1), \\ x_{ij}(c_1)x_{jk}(c_2) &= x_{jk}(c_2)x_{ij}(c_1)x_{ik}(c_1c_2), & x_{jk}(c_1)x_{ij}(c_2) &= x_{ij}(c_2)x_{jk}(c_1)x_{ik}(-c_1c_2), \end{aligned}$$

where $i < j < k$.

- Letting $h(d_1, \dots, d_n) = h_1(d_1) \cdots h_n(d_n)$, the h-past-y relation is

$$h(d_1, \dots, d_n)y_i(c) = y_i(cd_i d_{i+1}^{-1})h(d_1, \dots, d_{i-1}, d_{i+1}, d_i, d_{i+2}, \dots, d_n). \quad (4.11)$$

- Letting $h(d_1, \dots, d_n) = h_1(d_1) \cdots h_n(d_n)$, the h-past-x relation is

$$h(d_1, \dots, d_n)x_{ij}(c) = x_{ij}(cd_i d_j^{-1})h(d_1, \dots, d_n). \quad (4.12)$$

- The x-past-y relations are

$$\begin{aligned} x_{i,i+1}(c_1)y_i(c_2) &= y_i(c_1 + c_2)x_{i,i+1}(0), \\ x_{ik}(c_1)y_k(c_2) &= y_k(c_2)x_{ik}(c_1c_2)x_{i,k+1}(c_1), & x_{i,k+1}(c_1)y_k(c_2) &= y_k(c_2)x_{ik}(c_1), \\ x_{ij}(c_1)y_i(c_2) &= y_i(c_2)x_{i+1,j}(c_1), & x_{i+1,j}(c_1)y_i(c_2) &= y_i(c_2)x_{ij}(c_1)x_{i+1,j}(-c_1c_2), \end{aligned} \quad (4.13)$$

where $i < k$ and $i + 1 < j$.

Proof. The proof of this result provides a way of writing an invertible matrix g in a “normal form” as a product of elementary matrices by the following “row reduction” algorithm.

Let $g \in GL_n(\mathbb{F})$.

Let $j_1 \in \{1, 2, \dots, n\}$ be maximal such that $g(j_1, 1) \neq 0$. If $j_1 = 1$ then let $g^{(1)} = g$. If $j_1 \neq 1$ then let

$$g^{(1)} = y_1 \left(\frac{g(1,1)}{g(j_1,1)} \right)^{-1} y_2 \left(\frac{g(1,2)}{g(j_1,1)} \right)^{-1} \cdots y_{j_1-1} \left(\frac{g(j_1-1,1)}{g(j_1,1)} \right)^{-1} g.$$

Now let $j_2 \in \{2, \dots, n\}$ be maximal such that $g^{(1)}(j_2, 2) \neq 0$. If $j_2 = 2$ then let $g^{(2)} = g^{(1)}$. If $j_2 \neq 2$ then let

$$g^{(2)} = y_2 \left(\frac{g^{(1)}(2,2)}{g^{(1)}(j_2,2)} \right)^{-1} y_3 \left(\frac{g^{(1)}(3,2)}{g^{(1)}(j_2,2)} \right)^{-1} \cdots y_{j_2-1} \left(\frac{g^{(1)}(j_2-1,2)}{g^{(1)}(j_2,2)} \right)^{-1} g^{(1)}.$$

Continuing this process will produce $g^{(n)}$ which has the property that

the first nonzero entry in row $j + 1$ is to the right of the first nonzero entry in row j .

In particular, if g is invertible then $g^{(n)}$ will be upper triangular.

Let $b = g^{(n)}$. Then

$$\begin{aligned} g &= \cdots (y_{j_2-1} \left(\frac{g^{(1)}(j_2-1,2)}{g^{(1)}(j_2,2)} \right) \cdots y_3 \left(\frac{g^{(1)}(3,2)}{g^{(1)}(j_1,2)} \right) y_2 \left(\frac{g^{(1)}(2,2)}{g^{(1)}(j_2,2)} \right)) \\ &\quad \cdot (y_{j_1-1} \left(\frac{g(j_1-1,1)}{g(j_1,1)} \right) \cdots y_2 \left(\frac{g(2,1)}{g(j_1,1)} \right) y_1 \left(\frac{g(1,1)}{g(j_1,1)} \right)) \cdot b \end{aligned}$$

Checking the relations: Recall that

$$y_i(c) = x_{i,i+1}(c)s_{i,i+1} = \begin{pmatrix} 1 & c \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} c & 1 \\ 1 & 0 \end{pmatrix}.$$

The reflection relations and the building relations are the relations for rearranging ys .

Proof of the reflection equation:

If $c_1 \neq 0$ and $c_2 \neq 0$ then

$$\begin{aligned} y_1(c_1)y_1(c_2) &= \begin{pmatrix} c_1 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} c_2 & 1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} c_1c_2 + 1 & c_1 \\ c_2 & 1 \end{pmatrix} \\ &= \begin{pmatrix} c_1 + c_2^{-1} & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} c_2 & 1 \\ 0 & -c_2^{-1} \end{pmatrix} = \begin{pmatrix} c_1 + c_2^{-1} & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} c_2 & 0 \\ 0 & -c_2^{-1} \end{pmatrix} \begin{pmatrix} 1 & c_2^{-1} \\ 0 & 1 \end{pmatrix} \\ &= y_1(c_1 + c_2^{-1})h_1(c_2)h_2(-c_2^{-1})x_{12}(c_2^{-1}). \end{aligned}$$

If $c_2 = 0$ then

$$y_1(c_1)y_1(0) = \begin{pmatrix} c_1 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} 1 & c_1 \\ 0 & 1 \end{pmatrix} = x_{12}(c_1).$$

Proof of the building relation:

$$\begin{aligned} \begin{pmatrix} c_1 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & c_2 & 1 \\ 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} c_3 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} &= \begin{pmatrix} c_1c_3 + c_2 & 1 & 0 \\ c_3 & 1 & 0 \\ 1 & 0 & 0 \end{pmatrix} \\ &= \begin{pmatrix} 1 & 0 & 0 \\ 0 & c_3 & 1 \\ 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} c_1c_3 + c_2 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & c_1 & 1 \\ 0 & 1 & 0 \end{pmatrix} \end{aligned}$$

The computation for the proof of the first x -interchange relation is:

$$\begin{pmatrix} 1 & c_1 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & c_2 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & c_1 + c_2 \\ 0 & 1 \end{pmatrix}$$

The key computation for the proof of the h -past- y relation is:

$$\begin{pmatrix} d_1 & 0 \\ 0 & d_2 \end{pmatrix} \begin{pmatrix} c & 1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} cd_1 & d_1 \\ d_2 & 0 \end{pmatrix} = \begin{pmatrix} cd_1d_2^{-1} & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} d_2 & 0 \\ 0 & d_1 \end{pmatrix}$$

Key computations for the proof of the x -past- y relations are:

$$\begin{aligned} \begin{pmatrix} 1 & c_1 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} c_2 & 1 \\ 1 & 0 \end{pmatrix} &= \begin{pmatrix} c_1 + c_2 & 1 \\ 1 & 0 \end{pmatrix}, \\ \begin{pmatrix} 1 & c_1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & c_2 & 1 \\ 0 & 1 & 0 \end{pmatrix} &= \begin{pmatrix} 1 & c_1c_2 & c_1 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & c_2 & 1 \\ 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & c_1c_2 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & c_1 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}, \\ \begin{pmatrix} 1 & 0 & c_1 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & c_2 & 1 \\ 0 & 1 & 0 \end{pmatrix} &= \begin{pmatrix} 1 & c_1 & 0 \\ 0 & c_2 & 1 \\ 0 & 1 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & c_2 & 1 \\ 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & c_1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}, \\ \begin{pmatrix} 1 & 0 & c_1 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} c_2 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 0 & 1 \end{pmatrix} &= \begin{pmatrix} c_2 & 1 & c_1 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} c_2 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & c_1 \\ 0 & 0 & 1 \end{pmatrix}, \\ \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & c_1 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} c_2 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 0 & 1 \end{pmatrix} &= \begin{pmatrix} c_2 & 1 & 0 \\ 1 & 0 & c_1 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} c_2 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & c_1 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & -c_1c_2 \\ 0 & 0 & 1 \end{pmatrix}. \end{aligned}$$

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