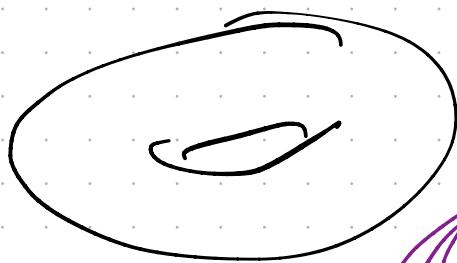


# GTLB Lecture 14.08.2020



CL(FV)

$\mathbb{R}$  as a  $\mathbb{Q}$ -vector space

## $\mathbb{K}$ -Vector spaces

### Subspaces.

Favorite example of an  $\mathbb{K}$ -vector space is  $\mathbb{K}^n$ :

$$\mathbb{K}^n = \left\{ \begin{pmatrix} g \\ \vdots \\ c_n \end{pmatrix} \mid c_1, \dots, c_n \in \mathbb{K} \right\}$$

with addition

$$\begin{pmatrix} g \\ \vdots \\ c_n \end{pmatrix} + \begin{pmatrix} d \\ \vdots \\ d_n \end{pmatrix} = \begin{pmatrix} g+d_1 \\ \vdots \\ c_n+d_n \end{pmatrix}$$

and scalar multiplication

$$c \begin{pmatrix} g \\ \vdots \\ c_n \end{pmatrix} = \begin{pmatrix} cg_1 \\ \vdots \\ cc_n \end{pmatrix}.$$

# Linear transformations

Linear transformations are for comparing vector spaces. Let  $\mathbb{F}$  be a field. Let  $V, W$  be  $\mathbb{F}$ -vector spaces.

A linear transformation between  $V$  and  $W$  is a function

$$f: V \rightarrow W$$

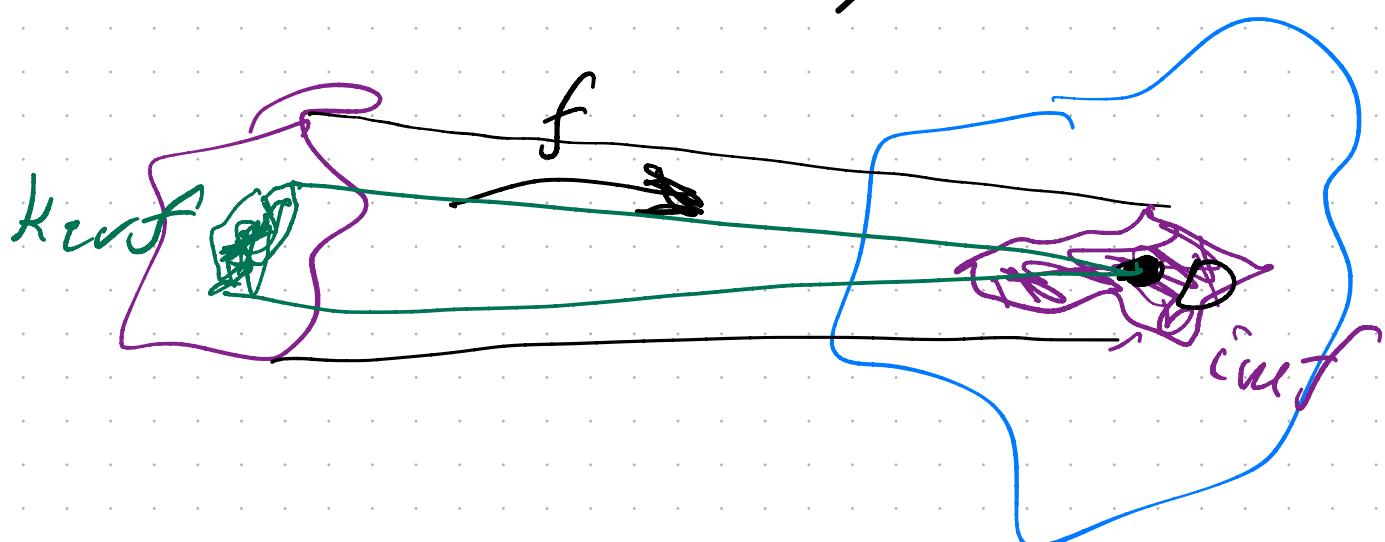
such that

(a) If  $v_1, v_2 \in V$  then

$$f(v_1 + v_2) = f(v_1) + f(v_2)$$

(b) If  $c \in \mathbb{F}$  and  $v \in V$  then

$$f(cv) = cf(v)$$



The image of  $f$  is

$$\text{im } f = \{f(v) \mid v \in V\}$$

The kernel of  $f$ , or nullspace of  $f$ ,

$$\text{ker } f = \{v \in V \mid f(v) = 0\}.$$

Theorem

- (a)  $\text{ker } f$  is a subspace of  $V$
- (b)  $\text{im } f$  is a subspace of  $W$ .

1<sup>st</sup> way of getting matrices from vector  
Matrix of linear transformation  
with respect to bases B and C

Let  $V, W$  be  $F$ -vector spaces

Let  $f: V \rightarrow W$  be a linear transformation.

Let  $B$  be a basis of  $V$

Let  $C$  be a basis of  $W$ .

The matrix of  $f$  with respect

to the bases B and C

is  $f_{CB}$  given by

$$f(b) = \sum_{c \in C} f_{CB}(c, b)c$$

for  $b \in B$

$f_{CB}(c, b)$ , is  $(c, b)$  entry of  
the matrix  $f_{CB}$ .

2<sup>nd</sup> way of getting matrices  
from vector spaces.

Let  $V$  be a ~~vector~~ space.

Let  $B$  and  $C$  two ~~diff~~  
bases of  $V$ .

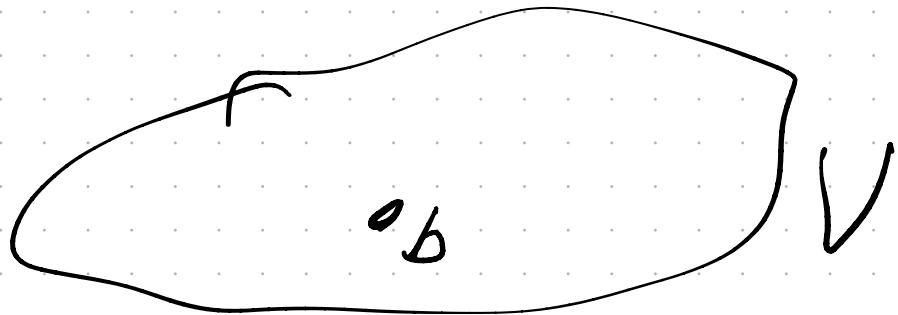
$$B = \{b_1, \dots, b_n\} \text{ and } C = \{c_1, \dots, c_n\}$$

The change of basis matrix  
from  $B$  to  $C$  is the matrix

$P_{CB}$  given by

$$\delta = \sum_{c \in C} P_{CB}(c, b) c$$

for  $b \in B$



$P_{CB}(c, b)$  is the  $(c, b)$  entry  
of the matrix  $P_{CB}$ .

Example Let  $\mathcal{F} = \mathcal{F}_5 = \{0, 1, 2, 3, 4\}$ .

$$V = \mathcal{F}_5^2 = \begin{pmatrix} 0 \\ 4 \end{pmatrix} \circ \circ \circ \circ \circ \begin{pmatrix} 4 \\ 0 \end{pmatrix}$$

$$0 \quad 1 \quad \cancel{2} \quad 3 \quad 4 \quad 0$$

$$(1) \quad 0 \quad 1 \quad \cancel{2} \quad 3 \quad 4 \quad 0$$

$$\begin{pmatrix} 0 \\ 0 \end{pmatrix} \quad 0 \quad 1 \quad \cancel{2} \quad 3 \quad 4 \quad \begin{pmatrix} 4 \\ 0 \end{pmatrix}$$

Favorite basis "standard basis"

$$B = \{b_1, b_2\} \text{ with } b_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}, b_2 = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

Another basis is

$$C = \{c_1, c_2\} \text{ with } c_1 = \begin{pmatrix} 2 \\ 3 \end{pmatrix}, c_2 = \begin{pmatrix} 4 \\ 0 \end{pmatrix}$$

$$b_1 = \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \underline{D} \cdot \underline{\begin{pmatrix} 2 \\ 3 \end{pmatrix}} + 4 \cdot \underline{\begin{pmatrix} 1 \\ 0 \end{pmatrix}} = Dc_1 + 4c_2$$

$$b_2 = \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \cancel{2} \cdot \cancel{\begin{pmatrix} 2 \\ 3 \end{pmatrix}} + 4 \cdot \cancel{\begin{pmatrix} 1 \\ 0 \end{pmatrix}} = \cancel{2}c_1 + 4c_2$$

The change of basis matrix  $P_{CB}$

is

$$P_{CB} = \begin{pmatrix} 0 & 2 \\ 4 & 4 \end{pmatrix}$$

$$c_1 = \begin{pmatrix} 2 \\ 3 \end{pmatrix} = 2 \begin{pmatrix} 1 \\ 0 \end{pmatrix} + 3 \begin{pmatrix} 0 \\ 1 \end{pmatrix} = 2b_1 + 3b_2$$

$$c_2 = \begin{pmatrix} 4 \\ 0 \end{pmatrix} = 4 \begin{pmatrix} 1 \\ 0 \end{pmatrix} + 0 \begin{pmatrix} 0 \\ 1 \end{pmatrix} = 4b_1 + Db_2$$

and so

$$P_{BC} = \begin{pmatrix} 2 & 4 \\ 3 & D \end{pmatrix}$$

Then

$$\begin{aligned} P_{BC} P_{CB} &= \begin{pmatrix} 2 & 4 \\ 3 & 0 \end{pmatrix} \begin{pmatrix} 0 & 2 \\ 4 & 4 \end{pmatrix} \\ &= \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \end{aligned}$$

$$b_1 = 1b_1 + Db_2$$

$$b_2 = Db_1 + 1b_2$$

I've set up the notation

so that

$$P_{DC} P_{CB} = P_{DB}$$

$$\text{and } P_{BB} = I.$$

Note

$$P_{BC} = P_{CB}^{-1} \text{ since } P_{BC} P_{CB} = I.$$

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} For  
change  
of  
basis  
matrices.

Let  $g: V \rightarrow W$  be  
a linear transformation.

Let  $B$  a basis of  $V$

Let  $C$  a basis of  $W$ .

$g_B$  be the matrix of  $g$   
with respect to  $B$  and  $C$ .

Let  $X$  a basis  $V$

$Y$  a basis  $W$ .

What is  $g_{XY}$ ??

$$g_{yx} = P_{YL} g_{CB} P_{BX} \quad \boxed{\text{Useful.}}$$

If  $\mathbb{R}$  is integral domain  
(cancellation law)

then  $\mathbb{Q} = \left\{ \frac{a}{b} \mid a, b \in \mathbb{R}, b \neq 0 \right\}$

is field

$$\mathbb{R} \subseteq \mathbb{Q} \quad \mathbb{R}[x] \subseteq \mathbb{Q}[x].$$

$$\mathbb{Z} \subseteq \mathbb{Q}$$

$$\sqrt{2}x$$

What is a matrix?

$$A: B \times C \rightarrow \mathbb{F}$$

$$A: \{1, \dots, m\} \times \{1, \dots, n\} \rightarrow \mathbb{F}$$